

Dynamic Cone Penetration Test in Vacuum



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Enabling long-term human
presence in deep space



Outline

- Introduction
- Previous work
- Methods
- Results
- Analysis
- Discussion
- Summary and Conclusions
- Future work



Introduction

- Context
 - Geotechnical investigation ➤ Ground improvement ➤ Construction
 - Infrastructure
 - Landing and launch pads
 - Roads
 - Lunar base
 - Exploration and ISRU
- Potential geotechnical investigation methods on the Moon
 - Cone penetration
 - Vane shear
 - Plate load
 - Seismic
 - Ground penetrating radar
 - Boot imprints, trenches, boulder rolls, etc.



Introduction

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 - Infrastructure
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 - Lunar base
 - Space in-situ resource utilisation
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- Lunar environment
 - Regolith
 - Extreme temperatures
 - Radiation
 - Vacuum
 - Each location is unique
- Lunar analogue environment
 - Lunar regolith simulant
 - Homogeneous density
 - Earth's gravity
 - Lower vacuum

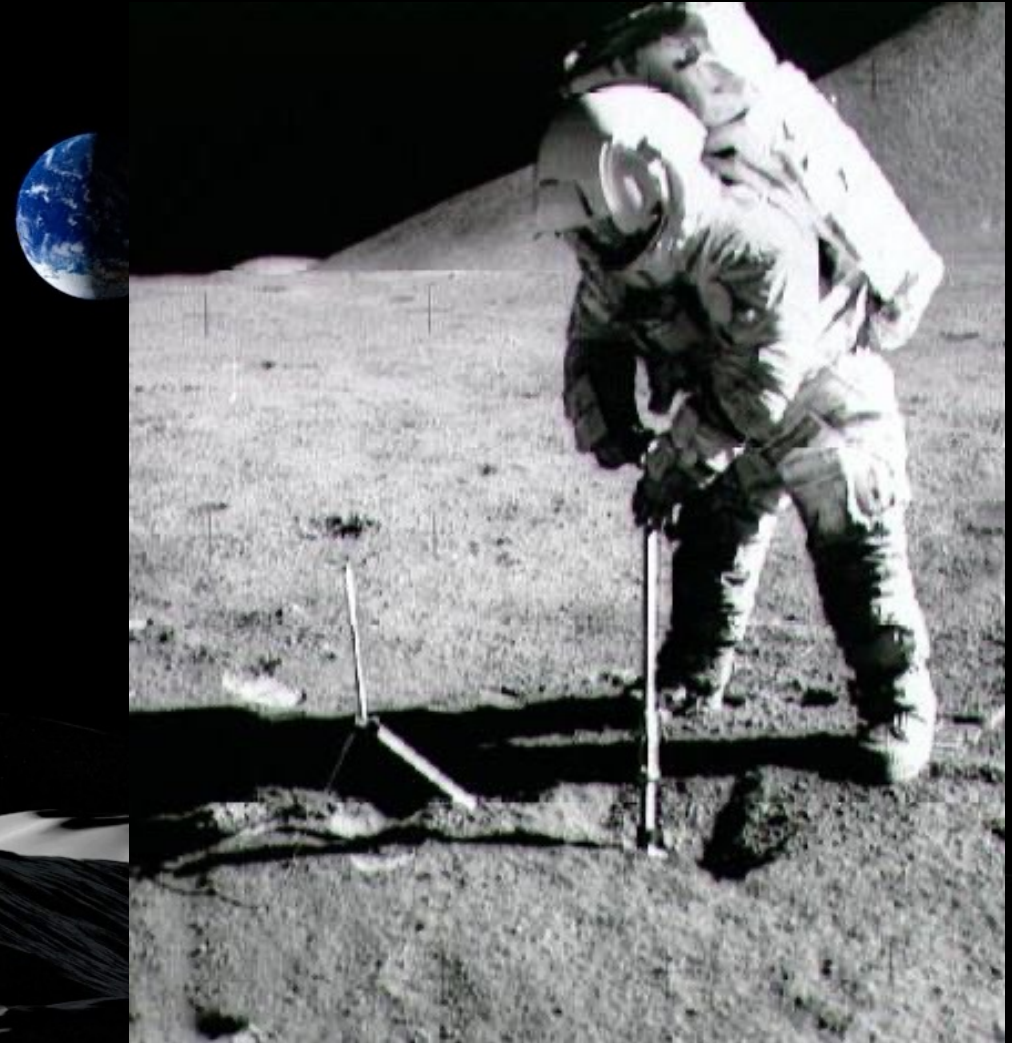
Introduction – Cone penetration

- Purpose
 - Stratigraphy and soil identification
 - Geotechnical investigation – density, stress, strength, etc.
 - Quality control
- Cone penetration test (CPT) - static
- Dynamic cone penetration test (DCPT) – dynamic
- Significant difference - reaction force



Introduction – Cone penetration

- Purpose
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- Cone penetration test (CPT) - static
- Dynamic cone penetration test (DCPT) – dynamic
- Significant difference - reaction force
- Penetration resistance
 - Hammering energy and momentum
 - Cone shape and size
 - Relative density
 - Depth
 - Internal friction and cohesion
 - Boundary effects
- Penetration history in space
 - Apollo 1969-1972
 - Lunokhod 1969-1973
 - Philae lander on Rosetta 2014
 - HP3 (Mole) on InSight 2018-2022



Lunar Self-Recording Penetrometer
test by Apollo 16 astronaut, NASA

Previous work



Filling regolith



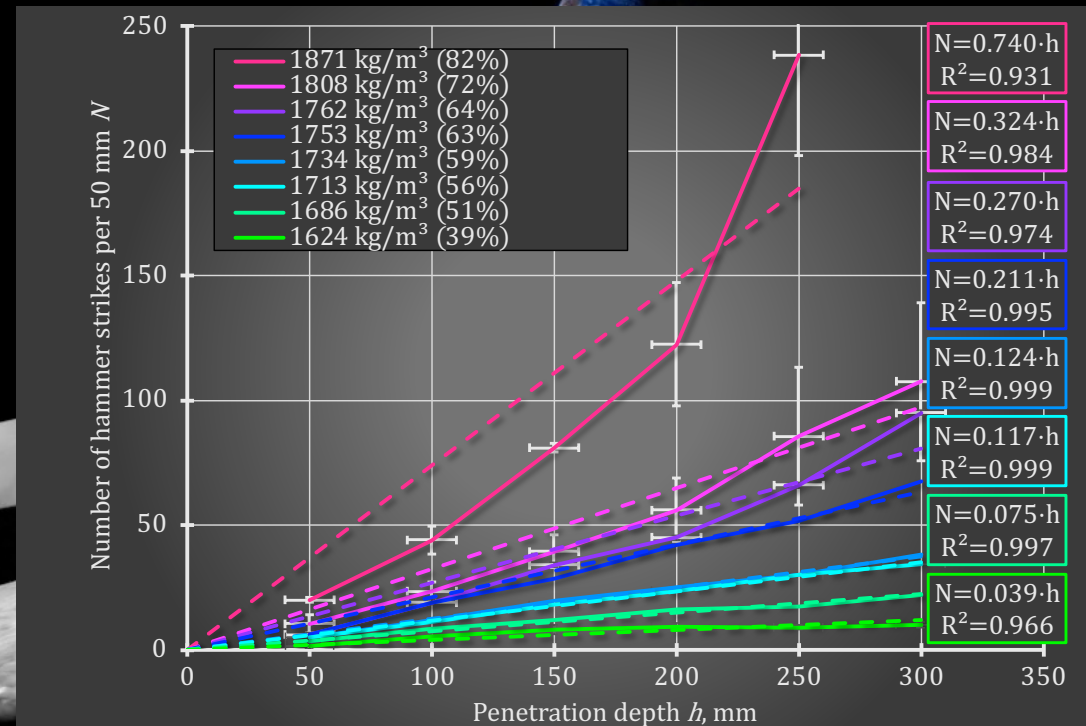
- Extraterrestrial Environmental Simulation (EXTERRES) laboratory at the Adelaide University
- Regolith pit with 8 tonnes of engineering grade lunar highlands regolith simulant (LHS-1E)
- 1 m³ regolith compaction chamber
- First large scale DCPT in regolith simulants



Compaction

Previous work cont.

- CPT and DCPT
- 12.7, 20.0, 27.5, 37.0 mm cone diameters
- Variable hammering energy



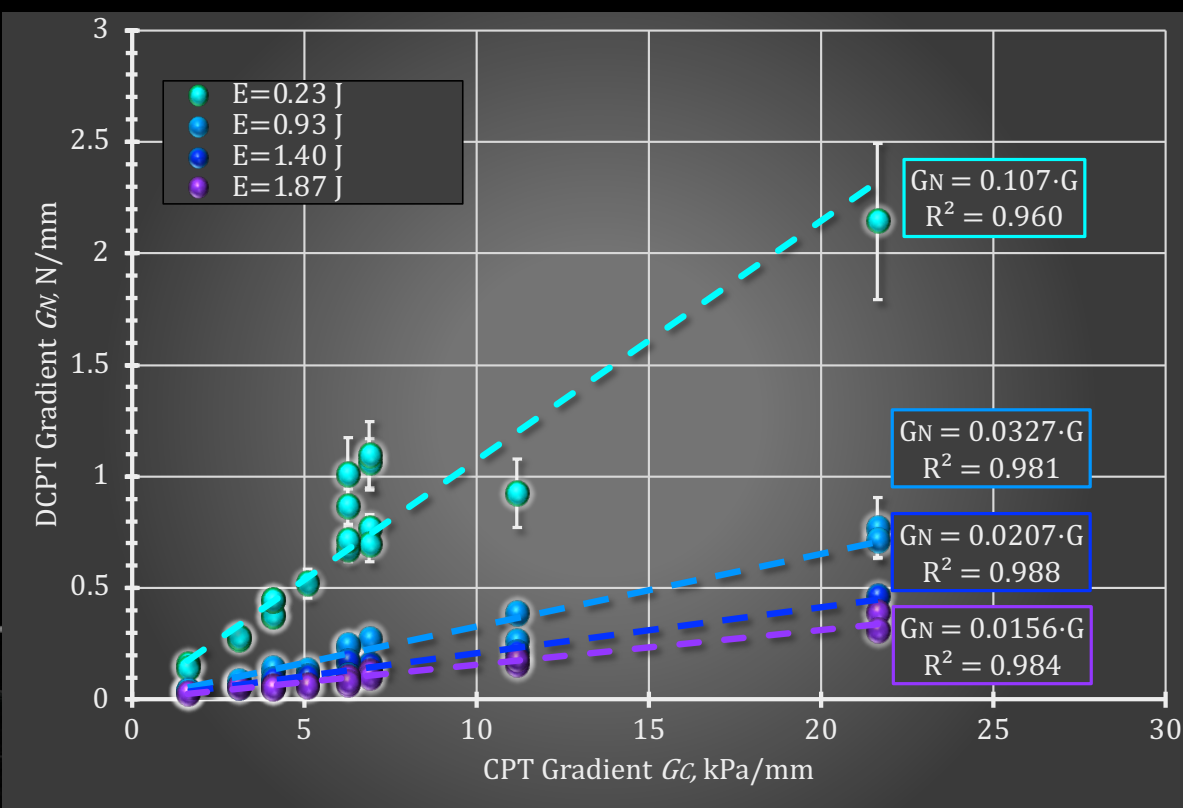
Mini-DCP hammer strikes per 50 mm versus depth



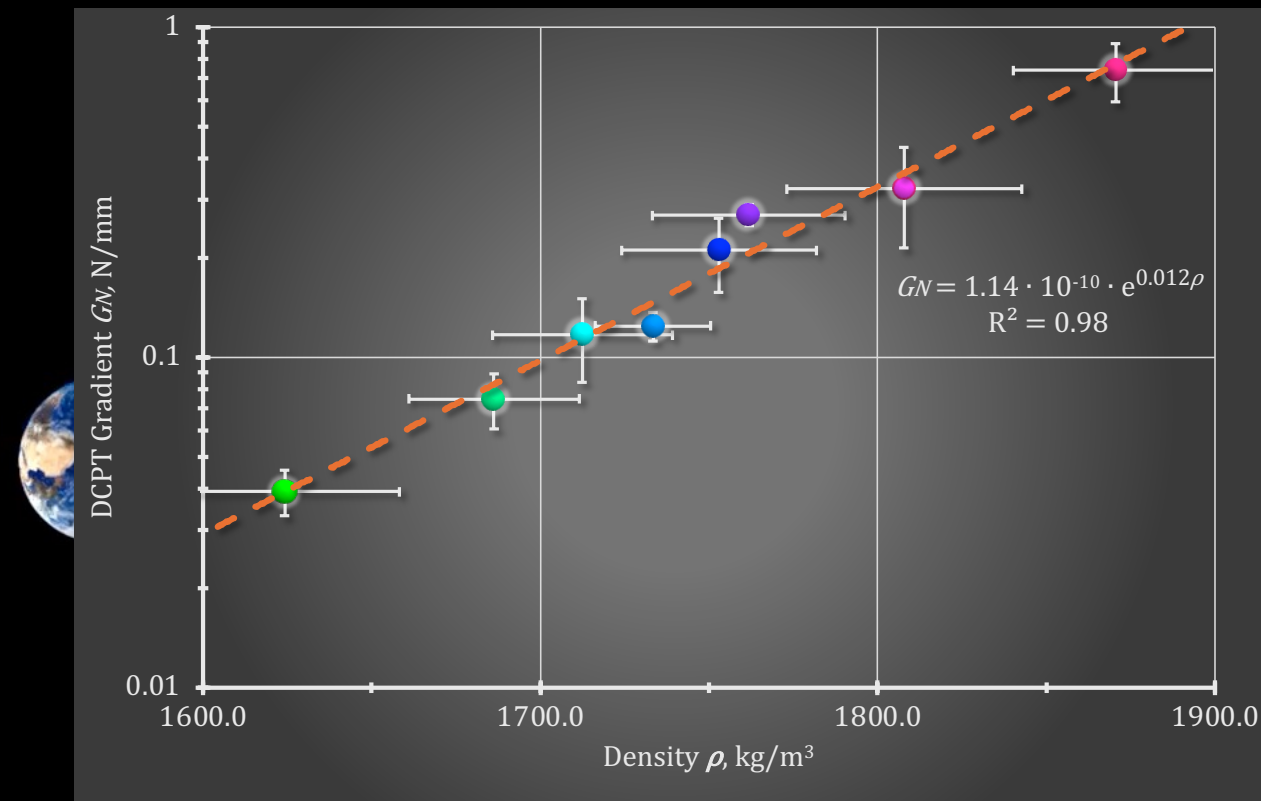
Mini dynamic cone penetrometer (Mini-DCP)

Previous results

- CPT and DCPT correlated
- LHS-1E at 1600 – 1900 kg/m³ densities



DCPT and CPT correlated at constant density and cone



DCPT Gradient and density at constant energy and cone

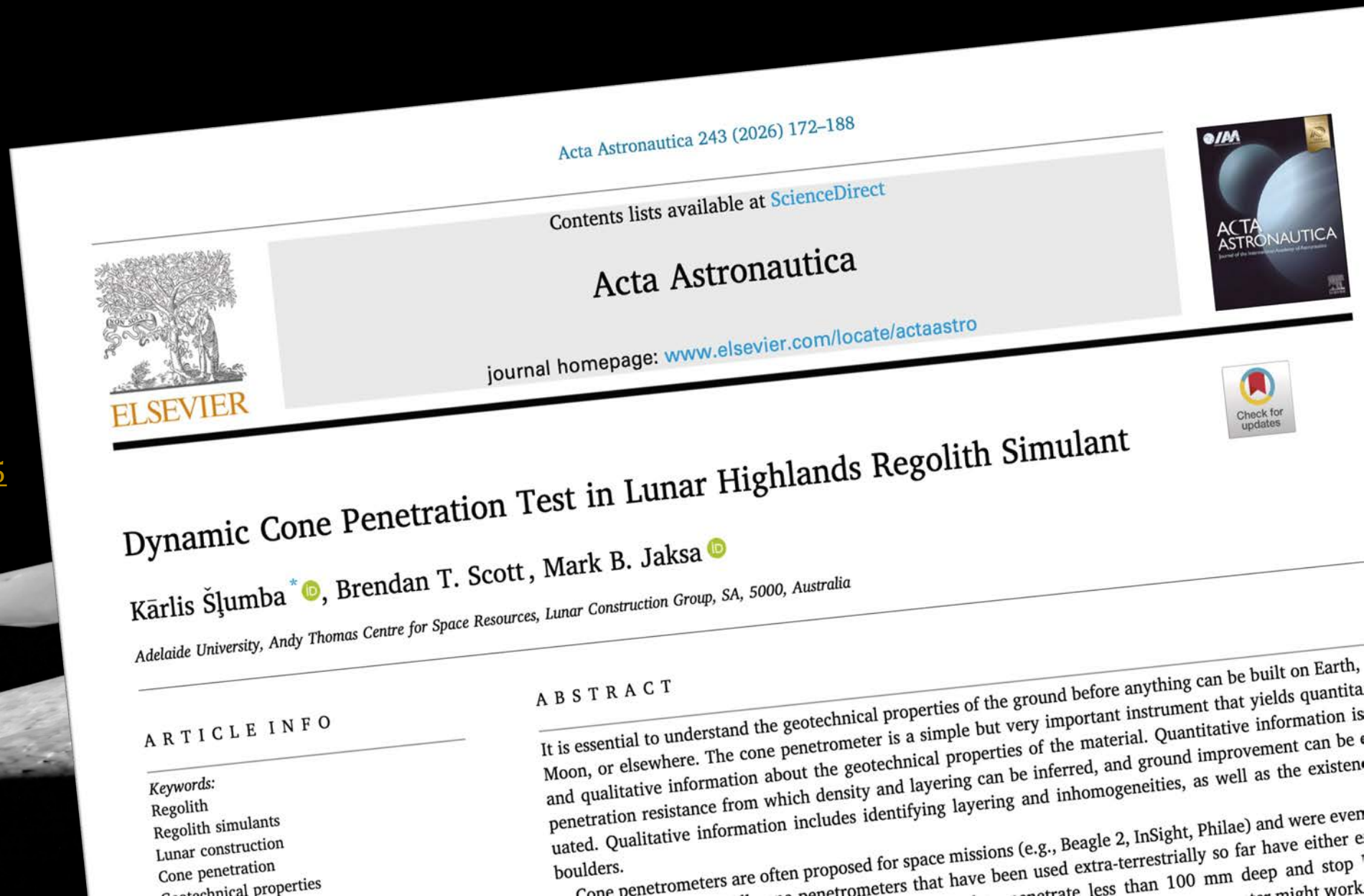
- Found optimal hammering energies
- DCP might be better for lunar exploration

Previous results published



Acta Astronautica paper DOI:
[10.1016/j.actaastro.2026.01.055](https://doi.org/10.1016/j.actaastro.2026.01.055)

4/June/2026



Methods - DCP

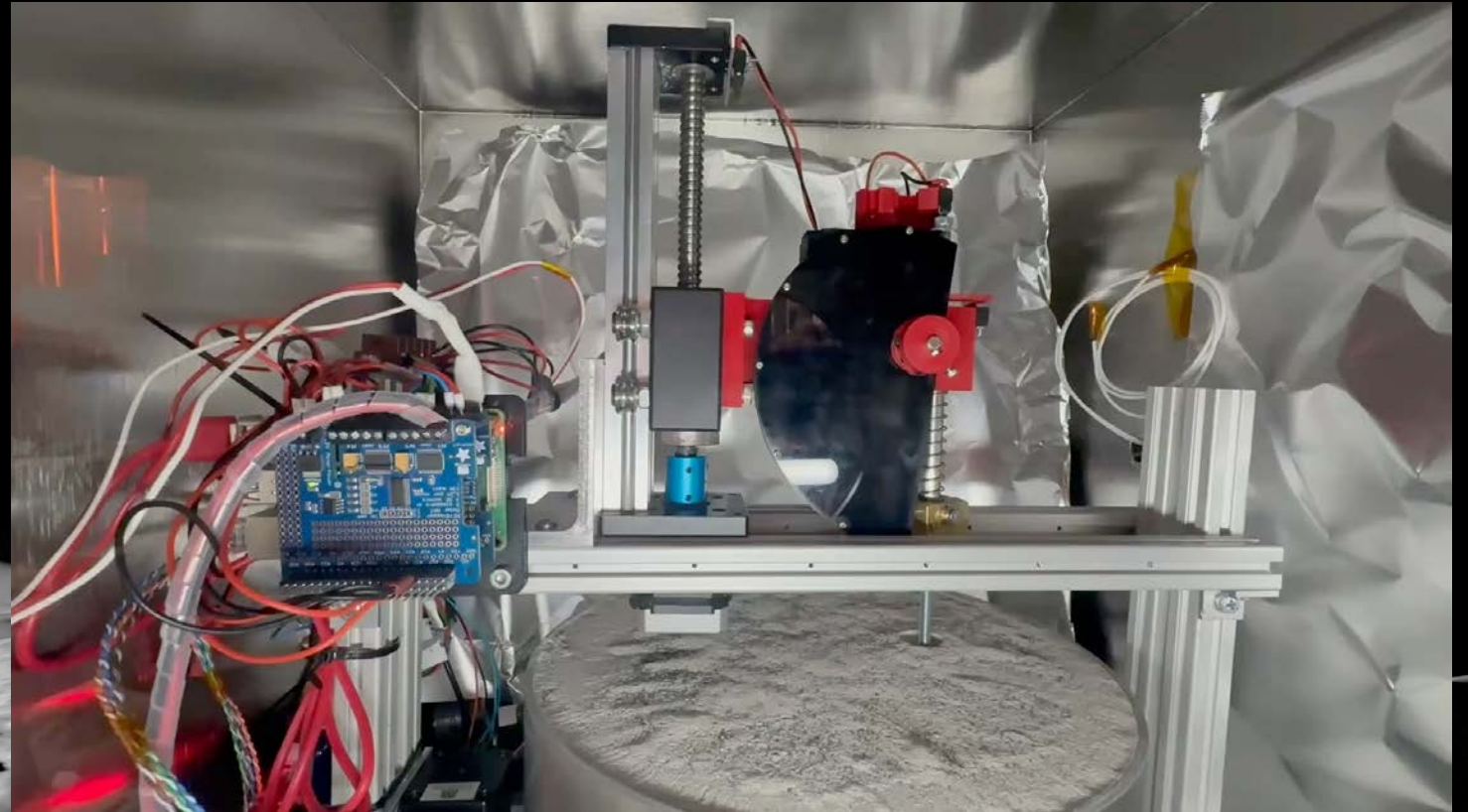
- Standard dynamic cone penetrometer
 - Total mass ~20 kg
 - Non-adjustable
- Mini dynamic cone penetrometer (Mini-DCP)
 - Total mass ~3.5 kg
 - Highly adjustable
 - Manual
- Vacuum dynamic cone penetrometer (Vac-DCP)
 - Robotic



Evolution of dynamic cone penetration

Methods – Vac-DCP

- Manufactured in-house at Adelaide University
- Fits inside 500 x 500 x 500 mm regolith thermal vacuum chamber (RTVac)
- Hammering action
 - Rotating cam lifts the hammer and compresses the spring
 - Hammer is accelerated by the spring and hits the anvil
 - Momentum is transferred to the cone
 - Depth is recorded
- Hammering energy 0.3 J
- Cone diameter 12.7 mm and 30° apex (Apollo cone)



Vac-DCP inside RTVac.

Methods – Sample

- Stainless steel container 266 mm diameter, 125 mm depth
- Oven-dried Lunar Highlands regolith simulant (LHS-1)
- Compaction in five 25 mm thick layers
- Penetrating until 100 mm depth
- Four tests per sample



Testing order

4/June/2026



Stainless steel container with LHS-1

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Plate compaction with Proctor hammer

Methods – Vacuum

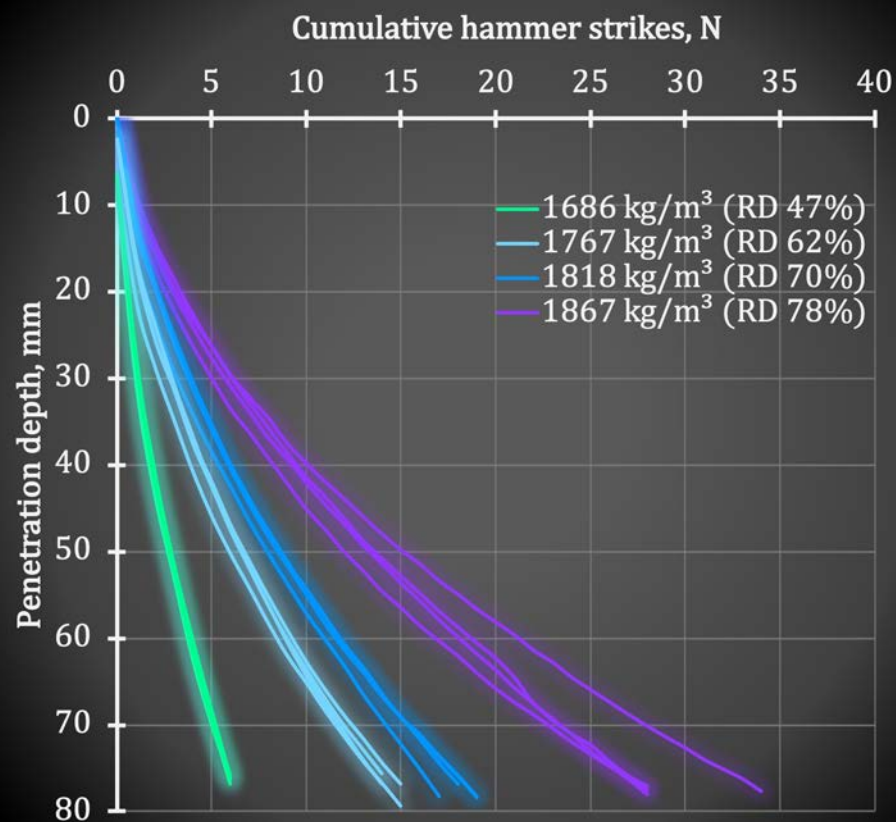
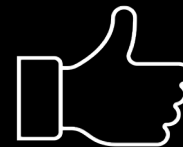
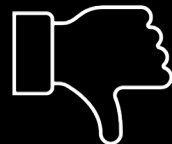
- High vacuum ($2.6 \cdot 10^{-5}$ to $3.0 \cdot 10^{-4}$ mBar)
- Slow – one test per day
- Avoiding outgassing
- Avoiding contamination
- Avoiding overheating
- No maintenance when under vacuum



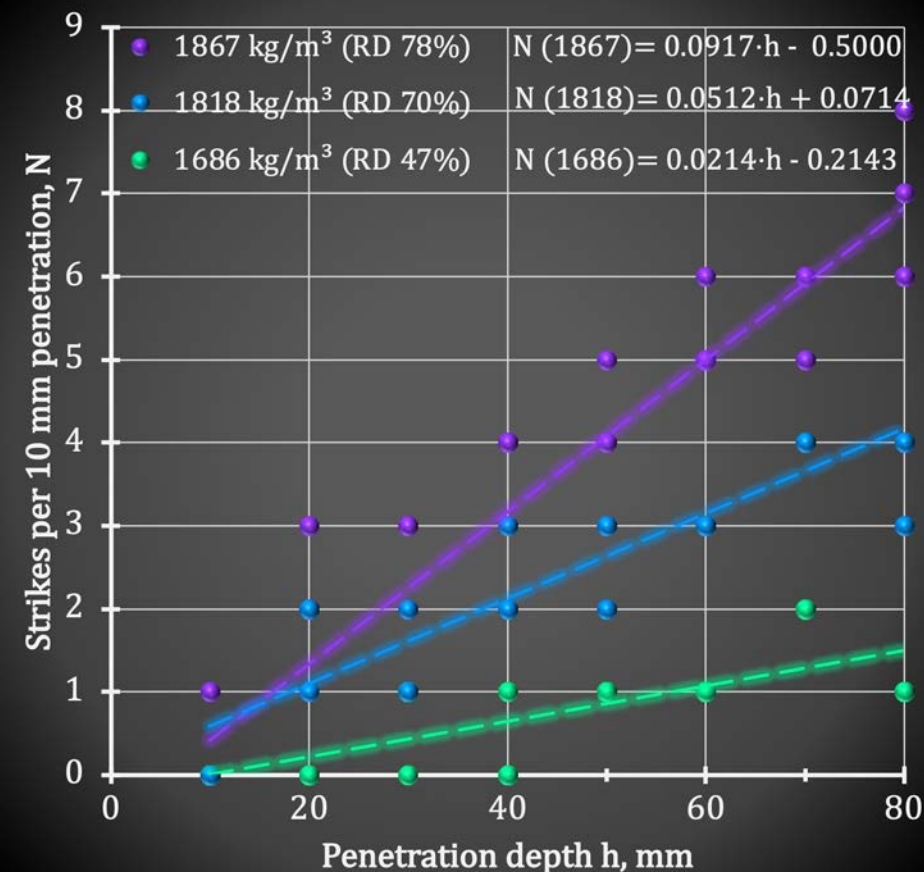
Vac-DCP inside RTVac.

Results

- 41 penetration in vacuum
- 63 penetrations in atmosphere
- Density range 1674 – 1893 kg/m³

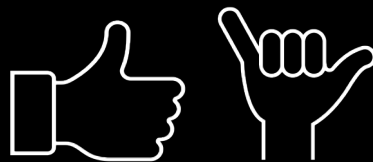


Cumulative hammer strikes

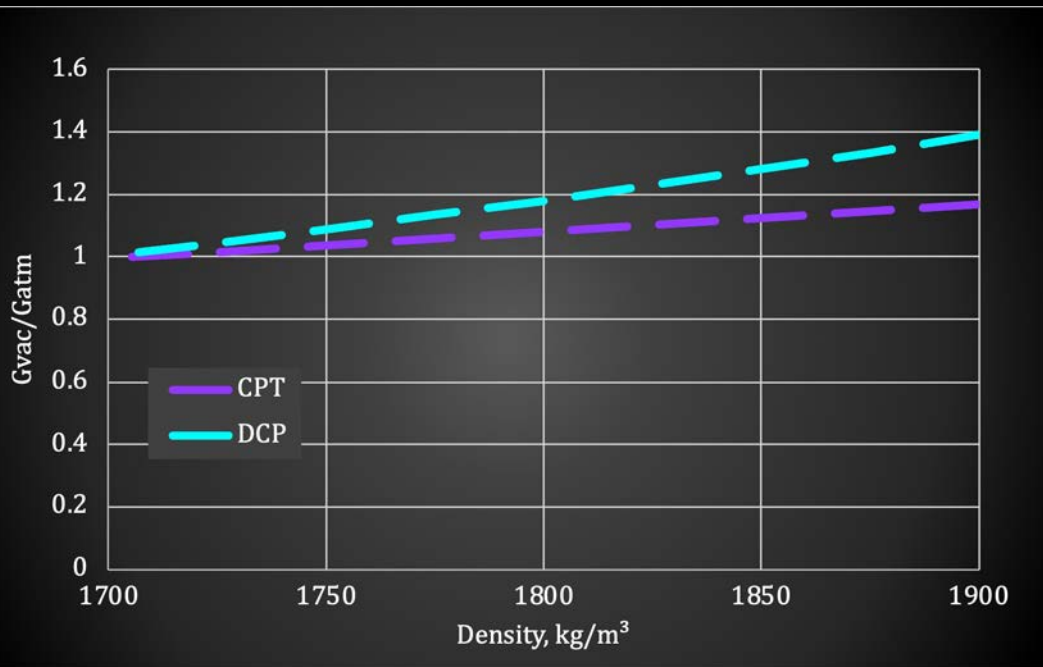


Hammer strikes per 10 mm penetration and gradient

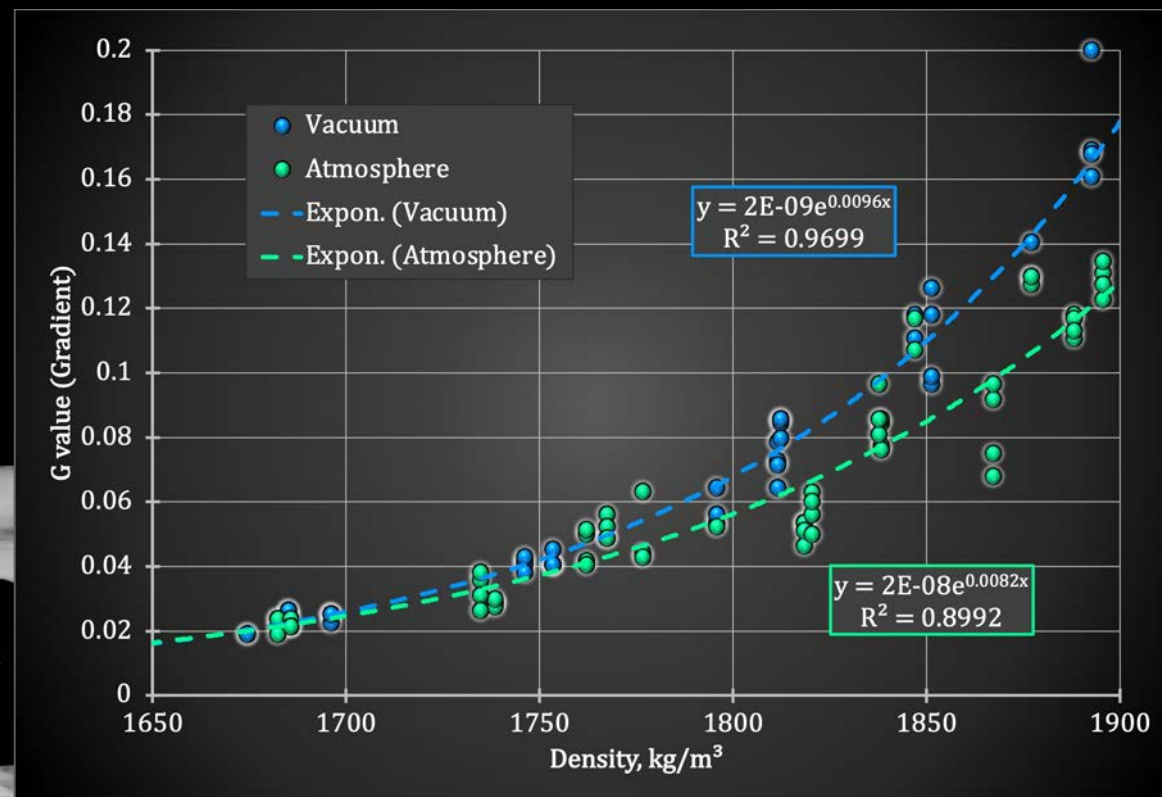
Analysis



- DCP gradient exponential with density
- Gradient / penetration resistance is higher in vacuum
- Gradient / penetration resistance increases with density
- Ratio = $\frac{G_{vac}}{G_{atm}}$



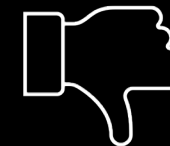
G_{vac} / G_{atm} ratio



DCP gradient and density

Discussion

- Vacuum effects on dynamic penetration difficult to predict
 - Capillary forces removed
 - Volatiles desorb
 - Van der Waals forces
- Pump down speed effect on the sample
 - Slow pump down
 - No disturbance observed
- Other results suggest that percussive and vibrating penetration resistance decreases in vacuum (Green et al. 2014, Rezich et al. 2025)
- Boundary effects eliminated



Summary and Conclusions

- First DCPT in vacuum
- TRL4 Vac-DCP, Vac-CPT, Vac-VST, Mini-DCP
- Dynamic cone penetration test results can be used to measure penetration resistance and density
- Dynamic cone penetrometer could be used and might be more applicable than static cone penetrometer for the geotechnical investigation in reduced gravity
- 300 N reaction force vs 30 hammer strikes to penetrate 100 mm deep in 1900 kg/m³



Future work

- More vacuum
- More Vac-DCP tests
- Vac-CPT
- Vac-VST
- Correlations between Vac-CPT and Vac-DCP



Vac-CPT

Keep playing in the sandbox!
It could take You to the Moon!



Abstract on ResearchGate

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References

- Background image “Earth and Sun from the Moon's South Pole” View from Shackleton Crater credits: NASA Scientific Visualization Studio https://svs.gsfc.nasa.gov/4944#section_credits
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- Green Alex, Zacny Kris (2014). Journal of Terramechanics, 51, 43–52
- Rezich Erin T. (2025). PhD Thesis Colorado School of Mines

